

Quantified Constraint Satisfaction Problem and H-Free Algorithmics

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Joint work with Tala Eagling-Vose, Santiago Guzman Pro, Barnaby Martin
and Yiming Qiu

Mathematics and Theoretical Physics Seminar

University of Hertfordshire

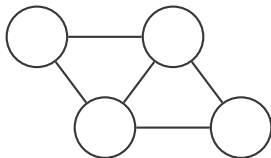
22 April 2026

1 Background

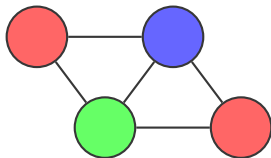
- Constraint Satisfaction Problem (CSP)
- Quantified Constraint Satisfaction Problem (QCSP)
- H-freeness

2 Our paper: Quantified Colouring and H-Free Algorithmics

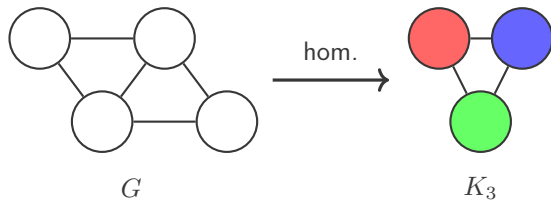
- $\text{QCSP}(K_3)$
- P_5 - and P_4 -free graphs
- The Line Graph of $K_{1,4}^r$



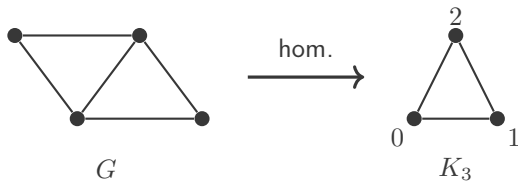
Colouring



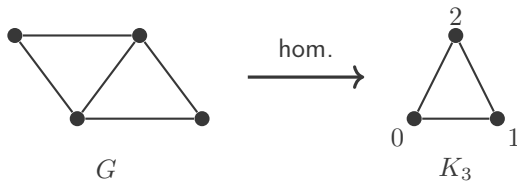
3-COLOURING



3-COLOURING, a.k.a. $\text{CSP}(K_3)$

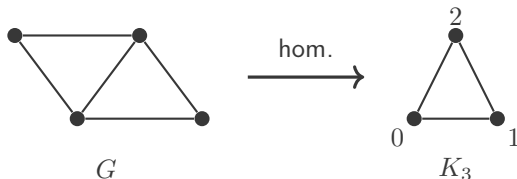


3-COLOURING, a.k.a. $\text{CSP}(K_3)$



$$\exists x_1 \exists x_2 \exists x_3 \exists x_4 (E(x_1, x_2) \wedge E(x_1, x_3) \wedge E(x_2, x_3) \wedge E(x_2, x_4) \wedge E(x_3, x_4))$$

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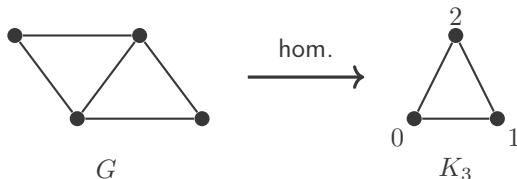


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$\text{CSP}(K_3)$:

- ▶ Input: a sentence ϕ that uses \exists, \wedge and the edge relation E
- ▶ Output: yes if $K_3 \models \phi$, no otherwise

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When A is finite, $\text{CSP}(A)$ is in NP.

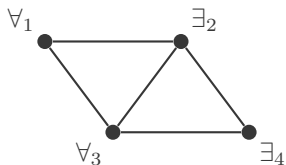
$\text{CSP}(K_3)$ is NP-complete.

QUANTIFIED 3-COLOURING, a.k.a. QCSP(K_3)

$$\forall x_1 \exists y_1 \forall x_2 \exists y_2 \dots \Phi$$

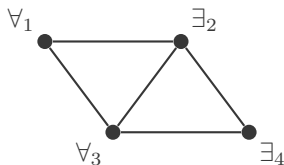
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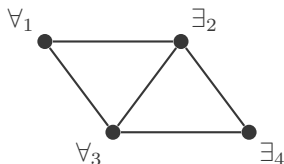
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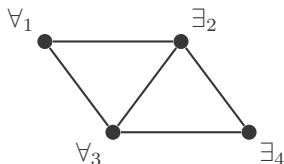
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QCSP(K_3):

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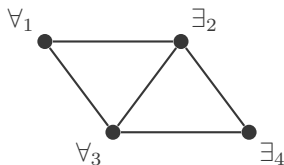
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When A is finite, QCSP(A) is in Pspace.

QCSP(K_3) is Pspace-complete.

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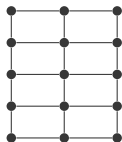
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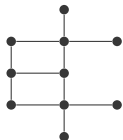
QCSP(K_3) is Pspace-complete.

QCSP captures games: Existential vs Universal players.

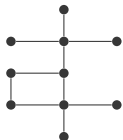
H -Free Graphs: Examples of Containment



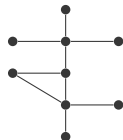
G



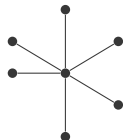
Induced subgraph
(vertex deletion)



Subgraph
(vertex deletion
and edge deletion)



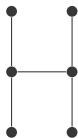
Topological minor
(vertex deletion,
edge deletion and
vertex dissolution
(degree 2 only))



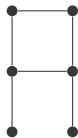
Minor
(vertex deletion,
edge deletion and
edge contraction)

If a graph G doesn't have some graph H as an induced subgraph, then we say that G is H -free.

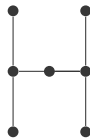
H -Free Graphs



H_1



H_1 -free
but not
 H_1 -subgraph-free



H_1 -subgraph-free
but not
 H_1 -minor-free

C123-framework (JMOPPSV 2025)

A graph problem Π satisfying the following conditions (the operation of *edge subdivision* replaces an edge with a path of some fixed length):

- C1.** Π is efficiently solvable for every graph class of bounded treewidth;
- C2.** Π is computationally hard for the class of subcubic graphs; and
- C3.** computational hardness is preserved under edge subdivision of subcubic graphs;

is called a *C123-problem*.

Let \mathcal{S} be the class of disjoint unions of subdivided claws or paths.

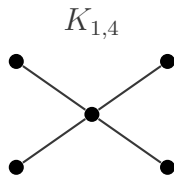
Theorem

Let Π be a C123-problem. For any finite set of graphs \mathcal{H} , the problem Π on \mathcal{H} -subgraph-free graphs is efficiently solvable if \mathcal{H} contains a graph from \mathcal{S} (or equivalently, if the class of \mathcal{H} -subgraph-free graphs has bounded treewidth) and computationally hard otherwise.

3-COLOURING

- ▶ $\text{CSP}(K_3)$ is NP-complete.
- ▶ $\text{CSP}(K_3)$ is in P for subcubic graphs (Brooks' Theorem).

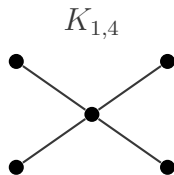
subcubic = maximum degree 3 = $K_{1,4}$ -subgraph-free



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- ▶ $\text{QCSP}(K_3)$ is Pspace-complete.
- ▶ $\text{QCSP}(K_3)$ on subcubic graphs?

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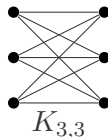
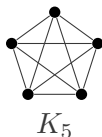
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QCSP(K_3): hardness results

Proposition

QCSP(K_3) is Pspace-complete on subcubic planar graphs.

planar = $\{K_5, K_{3,3}\}$ -minor-free

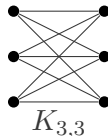
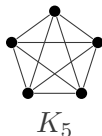


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Proposition

For $r \geq 3$ odd, Σ_r -QCSP(K_3) is Σ_{r-2}^P -hard on subcubic planar graphs.

Theorem

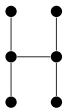
For $r \geq 3$ odd, the complexity of Σ_r -QCSP(K_3) on \mathcal{H} -topological-minor-free graphs is completely classified (even when \mathcal{H} is infinite). If \mathcal{H} contains some planar subcubic graph, then Σ_r -QCSP(K_3) is solvable in polynomial time; otherwise it is Σ_{r-2}^P -hard.

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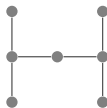
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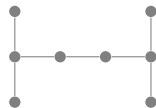
QCSP(K_3) is Pspace-complete on \mathbb{H}_1 -subgraph-free graphs.



H_1

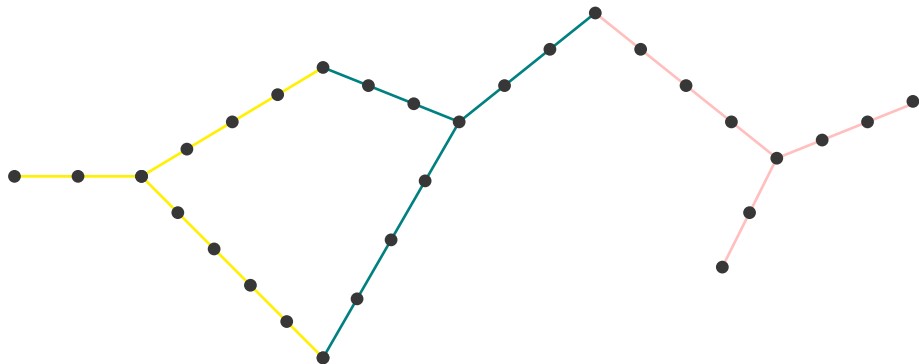


H_2



H_3

QCSP(K_3): tractability results



Proposition

QCSP(K_3) is in polynomial time on subcubic $\{\mathbb{H}_1, \mathbb{H}_2, \mathbb{H}_3, \mathbb{H}_4, \mathbb{H}_5, C_3, C_4\}$ -subgraph-free graphs.

Corollary: QCSP(K_3) is not a C123-problem.

P_4 - and P_5 -free Graphs

Theorem

If G is a finite graph, then $\text{QCSP}(G)$ restricted to inputs that are P_5 -free is in NP.

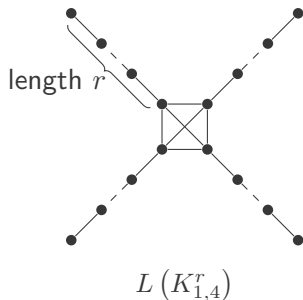


P_5

Proposition

$\text{QCSP}(K_3)$ is in polynomial time for inputs that are restricted to be P_4 -free.

The Line Graph of $K_{1,4}^r$



For $r \geq 8$:

m	The complexity of $\text{QCSP}(L(K_{1,4}^r))$ on P_m -free graphs
≤ 3	P
$r - 1$	NP-complete
$\geq 2r + 10$	Pspace-complete

The end

Thank you for your attention!